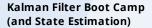


**4 Courses** 



Linear Kalman Filter Deep Dive (and Target Tracking)

Nonlinear Kalman Filters (and Parameter Estimation)

Particle Filters (and Navigation)



Dec 28, 2024

## **Raees Ahmad**

has successfully completed the online, non-credit Specialization

## **Applied Kalman Filtering**

To earn this certificate, participants must score 80% or higher on all graded quizzes. The specialization teaches participants how to design and implement Kalman filters for state estimation, target tracking, parameter estimation, and navigation applications. Participants learn how to derive linear Kalman filters, nonlinear (extended, sigma-point, unscented, and cubature) Kalman filters, and particle filters, and implement them in Octave code. A focus is placed on understanding how to modify the standard algorithm steps for applications that might not meet the standard assumptions and on how to implement robust solutions.

Dr. Gregory L. Plett Professor, Department of Electrical and Computer Engineering University of Colorado Colorado Springs

The online specialization named in this certificate may draw on material from courses taught on-campus, but the included courses are not equivalent to on-campus courses. Participation in this online specialization does not constitute enrollment at this university. This certificate does not confer a University grade, course credit or degree, and it does not verify the identity of the learner.

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